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## LMV321 / LMV358 / LMV324 Single/Dual/Quad General Purpose, Low Voltage, Rail-to-Rail Output Operational Amplifiers

## General Description

The LMV358/324 are low voltage (2.7-5.5V) versions of the dual and quad commodity op amps, LM358/324, which currently operate at $5-30 \mathrm{~V}$. The LMV321 is the single version.
The LMV321/358/324 are the most cost effective solutions for the applications where low voltage operation, space saving and low price are needed. They offer specifications that meet or exceed the familiar LM358/324. The LMV321/358/324 have rail-to-rail output swing capability and the input common-mode voltage range includes ground. They all exhibit excellent speed-power ratio, achieving 1 MHz of bandwidth and $1 \mathrm{~V} / \mu \mathrm{s}$ of slew rate with low supply current.
The LMV321 is available in space saving SC70-5, which is approximately half the size of SOT23-5. The small package saves space on pc boards, and enables the design of small portable electronic devices. It also allows the designer to place the device closer to the signal source to reduce noise pickup and increase signal integrity.
The chips are built with National's advanced submicron silicon-gate BiCMOS process. The LMV321/358/324 have bipolar input and output stages for improved noise performance and higher output current drive.

## Features

(For $\mathrm{V}^{+}=5 \mathrm{~V}$ and $\mathrm{V}^{-}=0 \mathrm{~V}$, Typical Unless Otherwise Noted)
$\square$ Guaranteed 2.7V and 5V Performance
$\square$ No Crossover Distortion
$\square$ Space Saving Package
$\square$ Industrial Temp.Range
SC70-5 2.0x2.1x1.0mm
$\square$ Gain-Bandwidth Product $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$

1 MHz
$\square$ Low Supply Current
LMV321
$130 \mu \mathrm{~A}$
LMV358
$210 \mu \mathrm{~A}$
$410 \mu \mathrm{~A}$
$\square$ Rail-to-Rail Output Swing
@ 10k $\Omega$ Load
$\mathrm{V}^{+}-10 \mathrm{mV}$
$\mathrm{V}^{-}+65 \mathrm{mV}$
-0.2 V to $\mathrm{V}^{+}-0.8 \mathrm{~V}$

## Applications

- Active Filters
- General Purpose Low Voltage Applications
- General Purpose Portable Devices



## Gain and Phase vs

 Capacitive Load

Absolute Maximum Ratings (Note 1)
If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

| ESD Tolerance (Note 2) |  |
| :--- | ---: |
| Machine Model | 100 V |
| Human Body Model |  |
| LMV358/324 | 2000 V |
| LMV321 | 900 V |
| Differential Input Voltage | $\pm$ Supply Voltage |
| Supply Voltage $\left(\mathrm{V}^{+}-\mathrm{V}^{-}\right)$ | 5.5 V |
| Output Short Circuit to V |  |
| Output Short Circuit to V - | (Note 3) |
| Soldering Information | (Note 4) |
| Infrared or Convection (20 sec) | $235^{\circ} \mathrm{C}$ |

Machine Model 100V
Human Body Model
LMV358/32
2000V
900 V
5.5 V
(Note 3)
(Note 4)
$235^{\circ} \mathrm{C}$

Storage Temp. Range $\quad-65^{\circ} \mathrm{C}$ to $150^{\circ} \mathrm{C}$
Junction Temp. ( $\mathrm{T}_{\mathrm{j}}$, max) (Note 5) $150^{\circ} \mathrm{C}$

## Operating Ratings (Note 1)

| Supply Voltage | 2.7 V to 5.5 V |
| :--- | ---: |
| Temperature Range |  |
| LMV321, LMV358, LMV324 | $-40^{\circ} \mathrm{C} \leq \mathrm{T}_{J} \leq 85^{\circ} \mathrm{C}$ |

Thermal Resistance ( $\theta$ JA) (Note 10)

| 5 -pin SC70-5 | $478^{\circ} \mathrm{C} / \mathrm{W}$ |
| :--- | :--- |
| 5-pin SOT23-5 | $265^{\circ} \mathrm{C} / \mathrm{W}$ |
| 8-Pin SOIC | $190^{\circ} \mathrm{C} / \mathrm{W}$ |
| 8-Pin MSOP | $235^{\circ} \mathrm{C} / \mathrm{W}$ |
| 14-Pin SOIC | $145^{\circ} \mathrm{C} / \mathrm{W}$ |
| 14-Pin TSSOP | $155^{\circ} \mathrm{C} / \mathrm{W}$ |

### 2.7V DC Electrical Characteristics

Unless otherwise specified, all limits guaranteed for $\mathrm{T}_{J}=25^{\circ} \mathrm{C}, \mathrm{V}^{+}=2.7 \mathrm{~V}, \mathrm{~V}^{-}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=1.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{O}}=\mathrm{V}^{+} / 2$ and $\mathrm{R}_{\mathrm{L}}>1 \mathrm{M} \Omega$.

| Symbol | Parameter | Conditions | $\begin{gathered} \text { Typ } \\ \text { (Note 6) } \end{gathered}$ | Limit (Note 7) | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {OS }}$ | Input Offset Voltage |  | 1.7 | 7 | $\begin{aligned} & \mathrm{mV} \\ & \max \end{aligned}$ |
| $\mathrm{TCV}_{\text {os }}$ | Input Offset Voltage Average Drift |  | 5 |  | $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ |
| $\mathrm{I}_{\mathrm{B}}$ | Input Bias Current |  | 11 | 250 | $\mathrm{nA}$ $\max$ |
| los | Input Offset Current |  | 5 | 50 | nA max |
| CMRR | Common Mode Rejection Ratio | $\mathrm{OV} \leq \mathrm{V}_{\mathrm{CM}} \leq 1.7 \mathrm{~V}$ | 63 | 50 | $\begin{aligned} & \mathrm{dB} \\ & \mathrm{~min} \end{aligned}$ |
| PSRR | Power Supply Rejection Ratio | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}^{+} \leq 5 \mathrm{~V} \\ & \mathrm{~V}_{\mathrm{O}}=1 \mathrm{~V} \end{aligned}$ | 60 | 50 | $\begin{aligned} & \hline \mathrm{dB} \\ & \mathrm{~min} \end{aligned}$ |
| $\mathrm{V}_{\mathrm{CM}}$ | Input Common-Mode Voltage Range | For CMRR $\geq 50 \mathrm{~dB}$ | -0.2 | 0 | $\begin{gathered} \mathrm{V} \\ \mathrm{~min} \end{gathered}$ |
|  |  |  | 1.9 | 1.7 | $\begin{gathered} \mathrm{V} \\ \max \end{gathered}$ |
| $\mathrm{V}_{\mathrm{O}}$ | Output Swing | $\mathrm{R}_{\mathrm{L}}=10 \mathrm{k} \Omega$ to 1.35 V | $\mathrm{V}^{+}-10$ | $\mathrm{V}^{+}-100$ | $\begin{aligned} & \mathrm{mV} \\ & \mathrm{~min} \end{aligned}$ |
|  |  |  | 60 | 180 | $\begin{aligned} & \mathrm{mV} \\ & \max \end{aligned}$ |
| $\mathrm{I}_{\mathrm{s}}$ | Supply Current | LMV321 | 80 | 170 | $\begin{gathered} \mu \mathrm{A} \\ \max \end{gathered}$ |
|  |  | LMV358 Both amplifiers | 140 | 340 | $\begin{gathered} \mu \mathrm{A} \\ \max \end{gathered}$ |
|  |  | LMV324 <br> All four amplifiers | 260 | 680 | $\begin{gathered} \mu \mathrm{A} \\ \max \end{gathered}$ |

### 2.7V AC Electrical Characteristics

Unless otherwise specified, all limits guaranteed for $\mathrm{T}_{\mathrm{J}}=25^{\circ} \mathrm{C}, \mathrm{V}^{+}=2.7 \mathrm{~V}, \mathrm{~V}^{-}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=1.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{O}}=\mathrm{V}^{+} / 2$ and $\mathrm{R}_{\mathrm{L}}>1 \mathrm{M} \Omega$.

| Symbol | Parameter | Conditions | Typ <br> (Note 6) | Limit <br> (Note 7) | Units |
| :--- | :--- | :--- | :---: | :---: | :---: |
| GBWP | Gain-Bandwidth Product | $\mathrm{C}_{\mathrm{L}}=200 \mathrm{pF}$ | 1 |  | MHz |
| $\Phi_{\mathrm{m}}$ | Phase Margin |  | 60 |  | Deg |
| $\mathrm{G}_{\mathrm{m}}$ | Gain Margin |  | 10 |  | dB |
| $\mathrm{e}_{\mathrm{n}}$ | Input-Referred Voltage Noise | $\mathrm{f}=1 \mathrm{kHz}$ | 46 |  | $\frac{\mathrm{nV}}{\sqrt{\mathrm{Hz}}}$ |
| $\mathrm{i}_{\mathrm{n}}$ | Input-Referred Current Noise | $\mathrm{f}=1 \mathrm{kHz}$ | 0.17 |  | $\frac{\mathrm{pA}}{\sqrt{\mathrm{Hz}}}$ |

## 5V DC Electrical Characteristics

Unless otherwise specified, all limits guaranteed for $T_{J}=25^{\circ} \mathrm{C}, \mathrm{V}^{+}=5 \mathrm{~V}, \mathrm{~V}^{-}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=2.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{O}}=\mathrm{V}^{+} / 2$ and $\mathrm{R}_{\mathrm{L}}>1 \mathrm{M} \Omega$.
Boldface limits apply at the temperature extremes


## 5V AC Electrical Characteristics

Unless otherwise specified, all limits guaranteed for $\mathrm{T}_{\mathrm{J}}=25^{\circ} \mathrm{C}, \mathrm{V}^{+}=5 \mathrm{~V}, \mathrm{~V}^{-}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=2.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{O}}=\mathrm{V}^{+} / 2$ and $\mathrm{R}_{\mathrm{L}}>1 \mathrm{M} \Omega$. Boldface limits apply at the temperature extremes.

| Symbol | Parameter | Conditions | Typ <br> $($ Note 6) | Limit <br> (Note 7) | Units |
| :--- | :--- | :--- | :---: | :---: | :---: |
| SR | Slew Rate | (Note 9) | 1 |  | $\mathrm{~V} / \mathrm{ss}$ |
| GBWP | Gain-Bandwidth Product | $\mathrm{C}_{\mathrm{L}}=200 \mathrm{pF}$ | 1 |  | MHz |
| $\Phi_{\mathrm{m}}$ | Phase Margin |  | 60 |  | Deg |
| $\mathrm{G}_{\mathrm{m}}$ | Gain Margin | 10 |  | dB |  |
| $\mathrm{e}_{\mathrm{n}}$ | Input-Referred Voltage Noise | $\mathrm{f}=1 \mathrm{kHz}$, | 39 |  | $\frac{\mathrm{nV}}{\sqrt{\mathrm{Hz}}}$ |
| $\mathrm{i}_{\mathrm{n}}$ | Input-Referred Current Noise | $\mathrm{f}=1 \mathrm{kHz}$ | 0.21 |  | $\frac{\mathrm{pA}}{\sqrt{\mathrm{Hz}}}$ |

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics.
Note 2: Human body model, $1.5 \mathrm{k} \Omega$ in series with 100 pF . Machine model, $0 \Omega$ in series with 200 pF .
Note 3: Shorting output to $\mathrm{V}^{+}$will adversely affect reliability.
Note 4: Shorting output to $\mathrm{V}^{-}$will adversely affect reliability
Note 5: The maximum power dissipation is a function of $T_{J(\max )}, \theta_{J A}$, and $T_{A}$. The maximum allowable power dissipation at any ambient temperature is $P_{D}=$ $\left(T_{J(\max )}-T_{A}\right) / \theta_{J A}$. All numbers apply for packages soldered directly into a PC board.
Note 6: Typical values represent the most likely parametric norm.
Note 7: All limits are guaranteed by testing or statistical analysis.
Note 8: $R_{L}$ is connected to $\mathrm{V}^{-}$. The output voltage is $0.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{O}} \leq 4.5 \mathrm{~V}$.
Note 9: Connected as voltage follower with 3V step input. Number specified is the slower of the positive and negative slew rates
Note 10: All numbers are typical, and apply for packages soldered directly onto a PC board in still air.
Typical Performance Characteristics Unless otherwise specified, $\mathrm{V}_{\mathrm{S}}=+5 \mathrm{~V}$, single supply, $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$.

## Supply Current vs Supply Voltage (LMV321)



## Sourcing Current vs

 Output Voltage

Input Current vs Temperature


Sinking Current vs Output Voltage


Sourcing Current vs Output Voltage


Sinking Current vs Output Voltage


Typical Performance Characteristics Unless otherwise speciied, $\mathrm{V}_{\mathrm{s}}=+5 \mathrm{~V}$, single supply,
$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$. (Continued)


Input Current Noise vs Frequency


Input Voltage Noise vs Frequency


Crosstalk Rejection vs Frequency


CMRR vs Input Common Mode Voltage


Input Current Noise vs Frequency


PSRR vs Frequency


CMRR vs Input Common Mode Voltage


Typical Performance Characteristics Unless otherwise specified, $\mathrm{V}_{\mathrm{S}}=+5 \mathrm{~V}$, single supply,
$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$. (Continued)

## $\Delta \mathrm{V}_{\text {os }}$ Vs CMR



Input Voltage vs
Output Voltage


Open Loop Frequency Response vs Temperature

$\Delta \mathrm{V}$ os $\mathbf{v s} \mathbf{C M R}$


## Open Loop

Frequency Response



Input Voltage vs Output Voltage


Open Loop
Frequency Response


Gain and Phase vs Capacitive Load


Typical Performance Characteristics Unless otherwise specified, $\mathrm{V}_{\mathrm{s}}=+5 \mathrm{~V}$, single supply, $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$. (Continued)


DS100060-57

Non-Inverting Large
Signal Pulse Response


TIME ( $1 \mu \mathrm{~s} / \mathrm{div}$ )
DS100060-A0

## Non-Inverting Small <br> Signal Pulse Response



TIME ( $1 \mu \mathrm{~s} / \mathrm{div}$ )
DS100060-A3

Non-Inverting Large Signal Pulse Response


Non-Inverting Small Signal Pulse Response


TIME ( $1 \mu \mathrm{~s} / \mathrm{div}$ )
DS100060-89

Inverting Large Signal
Pulse Response


TIME ( $1 \mu \mathrm{~s} / \mathrm{div}$ )
DS100060-90

Non-Inverting Large Signal Pulse Response


Non-Inverting Small Signal Pulse Response


TIME ( $1 \mu \mathrm{~s} / \mathrm{div}$ )
DS100060-A2

Inverting Large Signal
Pulse Response


TIME ( $1 \mu \mathrm{~s} / \mathrm{div}$ )
DS100060-A4

Typical Performance Characteristics Unless otherwise specified, $\mathrm{V}_{\mathrm{S}}=+5 \mathrm{~V}$, single supply,
$T_{A}=25^{\circ} \mathrm{C}$. (Continued)

Inverting Large Signal
Pulse Response


Inverting Small Signal
Pulse Response


## Stability vs Capacitive Load



## Inverting Small Signal

 Pulse Response

Stability vs Capacitive Load


Stability vs Capacitive Load


Inverting Small Signal Pulse Response


Stability vs Capacitive Load


THD vs Frequency


Typical Performance Characteristics Unless otherwise specified, $\mathrm{v}_{\mathrm{s}}=+5 \mathrm{~V}$, single supply, $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$. (Continued)

Open Loop Output Impedance vs Frequency


Short Circuit Current vs Temperature (Sinking)


## Short Circuit Current vs Temperature (Sourcing)



## Application Notes

### 1.0 Benefits of the LMV321/358/324

Size. The small footprints of the LMV321/358/324 packages save space on printed circuit boards, and enable the design of smaller electronic products, such as cellular phones, pagers, or other portable systems. The low profile of the LMV321/358/324 make them possible to use in PCMCIA type III cards.
Signal Integrity. Signals can pick up noise between the signal source and the amplifier. By using a physically smaller amplifier package, the LMV321/358/324 can be placed closer to the signal source, reducing noise pickup and increasing signal integrity.
Simplified Board Layout. These products help you to avoid using long pc traces in your pc board layout. This means that no additional components, such as capacitors and resistors, are needed to filter out the unwanted signals due to the interference between the long pc traces.
Low Supply Current. These devices will help you to maximize battery life. They are ideal for battery powered systems.
Low Supply Voltage. National provides guaranteed performance at 2.7 V and 5 V . These guarantees ensure operation throughout the battery lifetime.
Rail-to-Rail Output. Rail-to-rail output swing provides maximum possible dynamic range at the output. This is particularly important when operating on low supply voltages.
Input Includes Ground. Allows direct sensing near GND in single supply operation.
The differential input voltage may be larger than $\mathrm{V}^{+}$without damaging the device. Protection should be provided to prevent the input voltages from going negative more than -0.3 V (at $25^{\circ} \mathrm{C}$ ). An input clamp diode with a resistor to the IC input terminal can be used.
Ease of Use \& No Crossover Distortion. The LMV321/ 358/324 offer specifications similar to the familiar LM324. In addition, the new LMV321/358/324 effectively eliminate the output crossover distortion. The scope photos in Figure 1 and Figure 2 compare the output swing of the LMV324 and the LM324 in a voltage follower configuration, with $\mathrm{V}_{\mathrm{s}}= \pm$ 2.5 V and $\mathrm{R}_{\mathrm{L}}(=2 \mathrm{k} \Omega)$ connected to GND. It is apparent that the crossover distortion has been eliminated in the new LMV324.


DS100060-97
FIGURE 1. Output Swing of LMV324


FIGURE 2. Output Swing of LM324

### 2.0 Capacitive Load Tolerance

The LMV321/358/324 can directly drive 200 pF in unity-gain without oscillation. The unity-gain follower is the most sensitive configuration to capacitive loading. Direct capacitive loading reduces the phase margin of amplifiers. The combination of the amplifier's output impedance and the capacitive load induces phase lag. This results in either an underdamped pulse response or oscillation. To drive a heavier capacitive load, circuit in Figure 3 can be used.

## Application Notes (Continued)



FIGURE 3. Indirectly Driving A Capacitive Load Using Resistive Isolation

In Figure 3, the isolation resistor $\mathrm{R}_{\text {Iso }}$ and the load capacitor $C_{L}$ form a pole to increase stability by adding more phase margin to the overall system. The desired performance depends on the value of $\mathrm{R}_{\text {ISO }}$. The bigger the $\mathrm{R}_{\text {ISO }}$ resistor value, the more stable Vout will be. Figure 4 is an output waveform of Figure 3 using $620 \Omega$ for $\mathrm{R}_{\text {ISO }}$ and 510 pF for $\mathrm{C}_{\mathrm{L}}$.


FIGURE 4. Pulse Response of the LMV324 Circuit in Figure 3

The circuit in Figure 5 is an improvement to the one in Figure 3 because it provides DC accuracy as well as AC stability. If there were a load resistor in Figure 3, the output would be voltage divided by $\mathrm{R}_{\text {ISO }}$ and the load resistor. Instead, in Figure 5, $R_{F}$ provides the DC accuracy by using feed-forward techniques to connect $V_{I N}$ to $R_{L}$. Caution is needed in choosing the value of $R_{F}$ due to the input bias current of the LMV321/358/324. $C_{F}$ and $\mathrm{R}_{\text {ISO }}$ serve to counteract the loss of phase margin by feeding the high frequency component of the output signal back to the amplifier's inverting input, thereby preserving phase margin in the overall feedback loop. Increased capacitive drive is possible by increasing the value of $C_{F}$. This in turn will slow down the pulse response.


FIGURE 5. Indirectly Driving A Capacitive Load with DC Accuracy

### 3.0 Input Bias Current Cancellation

The LMV321/358/324 family has a bipolar input stage. The typical input bias current of LMV321/358/324 is 15 nA with 5 V supply. Thus a $100 \mathrm{k} \Omega$ input resistor will cause 1.5 mV of error voltage. By balancing the resistor values at both inverting and non-inverting inputs, the error caused by the amplifier's input bias current will be reduced. The circuit in Figure 6 shows how to cancel the error caused by input bias current.


FIGURE 6. Cancelling the Error Caused by Input Bias Current

### 4.0 Typical Single-Supply Application Circuits

### 4.1 Difference Amplifier

The difference amplifier allows the subtraction of two voltages or, as a special case, the cancellation of a signal common to two inputs. It is useful as a computational amplifier, in making a differential to single-ended conversion or in rejecting a common mode signal.

Application Notes
(Continued)


FIGURE 7. Difference Amplifier

### 4.2 Instrumentation Circuits

The input impedance of the previous difference amplifier is set by the resistors $R_{1}, R_{2}, R_{3}$, and $R_{4}$. To eliminate the problems of low input impedance, one way is to use a voltage follower ahead of each input as shown in the following two instrumentation amplifiers.

### 4.2.1 Three-op-amp Instrumentation Amplifier

The quad LMV324 can be used to build a three-op-amp instrumentation amplifier as shown in Figure 8.


FIGURE 8. Three-op-amp Instrumentation Amplifier
The first stage of this instrumentation amplifier is a differential-input, differential-output amplifier, with two voltage followers. These two voltage followers assure that the input impedance is over $100 \mathrm{M} \Omega$. The gain of this instrumentation amplifier is set by the ratio of $R_{2} / R_{1} . R_{3}$ should equal $R_{1}$, and $R_{4}$ equal $R_{2}$. Matching of $R_{3}$ to $R_{1}$ and $R_{4}$ to $R_{2}$ affects the CMRR. For good CMRR over temperature, low drift resistors should be used. Making $\mathrm{R}_{4}$ slightly smaller than R 2 and adding a trim pot equal to twice the difference between $R_{2}$ and $R_{4}$ will allow the CMRR to be adjusted for optimum.

### 4.2.2 Two-op-amp Instrumentation Amplifier

A two-op-amp instrumentation amplifier can also be used to make a high-input-impedance dc differential amplifier (Figure 9) . As in the three-op-amp circuit, this instrumentation amplifier requires precise resistor matching for good CMRR. R4 should equal to R1 and R3 should equal R2.


DS100060-11
$V_{0}=\left(1+\frac{R 4}{R 3}\right)\left(V_{2}-V_{1}\right)$, where $R 1=R 4$ and $R 2=R 3$
As shown: $V_{0}=2\left(V_{2}-V_{1}\right)$
DS100060-35
FIGURE 9. Two-Op-amp Instrumentation Amplifier

### 4.3 Single-Supply Inverting Amplifier

There may be cases where the input signal going into the amplifier is negative. Because the amplifier is operating in single supply voltage, a voltage divider using $R_{3}$ and $R_{4}$ is implemented to bias the amplifier so the input signal is within the input common-mode voltage range of the amplifier. The capacitor $\mathrm{C}_{1}$ is placed between the inverting input and resistor $R_{1}$ to block the $D C$ signal going into the $A C$ signal source, $\mathrm{V}_{\text {IN }}$. The values of $\mathrm{R}_{1}$ and $\mathrm{C}_{1}$ affect the cutoff frequency, fc $=1 / 2 \pi R_{1} C_{1}$.
As a result, the output signal is centered around mid-supply (if the voltage divider provides $\mathrm{V}^{+} / 2$ at the non-inverting input). The output can swing to both rails, maximizing the signal-to-noise ratio in a low voltage system.


FIGURE 10. Single-Supply Inverting Amplifier

### 4.4 Active Filter

### 4.4.1 Simple Low-Pass Active Filter

The simple low-pass filter is shown in Figure 11. Its lowfrequency gain $(\omega \rightarrow 0)$ is defined by $-R_{3} / R_{1}$. This allows lowfrequency gains other than unity to be obtained. The filter has a $-20 \mathrm{~dB} /$ decade roll-off after its corner frequency fc. $R_{2}$ should be chosen equal to the parallel combination of $R_{1}$ and $\mathrm{R}_{3}$ to minimize errors due to bias current. The frequency response of the filter is shown in Figure 12.

Application Notes (Continued)


$$
\begin{aligned}
& A_{L}=-\frac{R_{3}}{R_{1}} \\
& f_{C}=\frac{1}{2 \pi R_{3} C_{1}} \\
& R_{2}=R_{1} \| R_{3} \\
& \text { DS } 100060-37
\end{aligned}
$$

FIGURE 11. Simple Low-Pass Active Filter


FIGURE 12. Frequency Response of Simple Low-Pass Active Filter in Figure 11
Note that the single-op-amp active filters are used in to the applications that require low quality factor, $Q(\leq 10)$, low frequency ( $\leq 5 \mathrm{kHz}$ ), and low gain ( $\leq 10$ ), or a small value for the product of gain times $Q(\leq 100)$. The op amp should have an open loop voltage gain at the highest frequency of interest at least 50 times larger than the gain of the filter at this frequency. In addition, the selected op amp should have a slew rate that meets the following requirement:

$$
\text { SlewRate } \geq 0.5 \times\left(\omega_{\mathrm{H}} \mathrm{~V}_{\text {OPP }}\right) \times 10^{-6} \mathrm{~V} / \mu \mathrm{sec}
$$

where $\omega_{\mathrm{H}}$ is the highest frequency of interest, and $\mathrm{V}_{\text {opp }}$ is the output peak-to-peak voltage.

### 4.4.2 Sallen-Key 2nd-Order Active Low-Pass Filter

The Sallen-Key 2nd-order active low-pass filter is illustrated in Figure 13. The dc gain of the filter is expressed as

$$
\begin{equation*}
A_{L P}=\frac{R_{3}}{R_{4}}+1 \tag{1}
\end{equation*}
$$

Its transfer function is

$$
\begin{equation*}
\frac{V_{\text {OUT }}}{V_{\text {IN }}}(S)=\frac{\frac{1}{C_{1} C_{2} R_{1} R_{2}} A_{L P}}{S^{2}+S\left(\frac{1}{C_{1} R_{1}}+\frac{1}{C_{1} R_{2}}+\frac{1}{C_{2} R_{2}}-\frac{A_{L P}}{C_{2} R_{2}}\right)+\frac{1}{C_{1} C_{2} R_{1} R_{2}}} \tag{2}
\end{equation*}
$$



FIGURE 13. Sallen-Key 2nd-Order Active Low-Pass Filter

The following paragraphs explain how to select values for $R_{1}, R_{2}, R_{3}, R_{4}, C_{1}$, and $C_{2}$ for given filter requirements, such as $A_{L P}, Q$, and $f_{c}$.
The standard form for a 2 nd-order low pass filter is

$$
\begin{equation*}
\frac{V_{\text {OUT }}}{V_{I N}}(S)=\frac{A_{L P} \omega_{c}{ }^{2}}{S^{2}+\left(\frac{\omega_{c}}{Q}\right) S+\omega_{c}{ }^{2}} \tag{3}
\end{equation*}
$$

where
Q: Pole Quality Factor
$\omega_{\mathrm{C}}$ : Corner Frequency
Comparison between the Equation (2) and Equation (3) yields

$$
\begin{gather*}
\omega_{c}{ }^{2}=\frac{1}{C_{1} C_{2} R_{1} R_{2}}  \tag{4}\\
\frac{\omega_{c}}{Q}=\frac{1}{C_{1} R_{1}}+\frac{1}{C_{1} R_{2}}+\frac{1}{C_{2} R_{2}}-\frac{A_{L P}}{C_{2} R_{2}} \tag{5}
\end{gather*}
$$

To reduce the required calculations in filter design, it is convenient to introduce normalization into the components and design parameters. To normalize, let $\omega_{\mathrm{C}}=\omega_{\mathrm{n}}=1 \mathrm{rad} / \mathrm{s}$, and $C_{1}=C_{2}=C_{n}=1 F$, and substitute these values into Equation (4) and Equation (5). From Equation (4), we obtain

$$
\begin{equation*}
R_{1}=\frac{1}{R_{2}} \tag{6}
\end{equation*}
$$

From Equation (5), we obtain

$$
\begin{equation*}
R_{2}=\frac{1 \pm \sqrt{1-4 Q^{2}\left(2-A_{\mathrm{LP}}\right)}}{2 Q} \tag{7}
\end{equation*}
$$

For minimum dc offset, $\mathrm{V}_{+}=\mathrm{V}$-, the resistor values at both inverting and non-inverting inputs should be equal, which means

$$
\begin{equation*}
R_{1}+R_{2}=\frac{R_{3} R_{4}}{R_{3}+R_{4}} \tag{8}
\end{equation*}
$$

From Equation (1) and Equation (8), we obtain

$$
\begin{equation*}
R_{3}=\left(R_{1}+R_{2}\right) A_{L P} \tag{9}
\end{equation*}
$$

Application Notes
(Continued)

$$
\begin{equation*}
R_{4}=\left(\frac{A_{L P}}{A_{L P}-1}\right)\left(R_{1}+R_{2}\right) \tag{10}
\end{equation*}
$$

The values of $C_{1}$ and $C_{2}$ are normally close to or equal to

$$
C=\frac{10}{f_{c}} \mu F
$$

As a design example:
Require: $A_{L P}=2, Q=1, f c=1 \mathrm{KHz}$
Start by selecting C1 and C2. Choose a standard value that is close to

$$
\begin{gathered}
C=\frac{10}{f_{c}} \mu \mathrm{~F} \\
C_{1}=C_{2}=\frac{10}{1 \times 10^{3}} \mu \mathrm{~F}=0.01 \mu \mathrm{~F}
\end{gathered}
$$

From Equations (6), (7), (9), (10),
$\mathrm{R}_{1}=1 \Omega$
$\mathrm{R}_{2}=1 \Omega$
$\mathrm{R}_{3}=4 \Omega$
$\mathrm{R}_{4}=4 \Omega$
The above resistor values are normalized values with $\omega_{\mathrm{n}}=1 \mathrm{rad} / \mathrm{s}$ and $\mathrm{C}_{1}=\mathrm{C}_{2}=\mathrm{C}_{\mathrm{n}}=1 \mathrm{~F}$. To scale the normalized cut-off frequency and resistances to the real values, two scaling factors are introduced, frequency scaling factor ( $\mathrm{k}_{\mathrm{f}}$ ) and impedance scaling factor $\left(\mathrm{k}_{\mathrm{m}}\right)$.

$$
\begin{gathered}
\mathrm{k}_{\mathrm{f}}=\frac{\omega_{c}}{\omega_{\mathrm{n}}}=\frac{2 \pi \times 1 \times 10^{3}}{1}=2 \pi \times 10^{3} \\
\mathrm{k}_{\mathrm{m}} \mathrm{k}_{\mathrm{f}}=\frac{\mathrm{cn}}{\mathrm{c} 1} \\
k_{m}=1.59 \times 10^{4}
\end{gathered}
$$

Scaled values:

$$
\begin{aligned}
& \mathrm{R}_{2}=\mathrm{R}_{1}=15.9 \mathrm{k} \Omega \\
& \mathrm{R}_{3}=\mathrm{R}_{4}=63.6 \mathrm{k} \Omega \\
& \mathrm{C}_{1}=\mathrm{C}_{2}=0.01 \mu \mathrm{~F}
\end{aligned}
$$

An adjustment to the scaling may be made in order to have realistic values for resistors and capacitors. The actual value used for each component is shown in the circuit.

### 4.4.3 2nd-order High Pass Filter

A 2nd-order high pass filter can be built by simply interchanging those frequency selective components ( $\mathrm{R}_{1}, \mathrm{R}_{2}$, $\mathrm{C}_{1}, \mathrm{C}_{2}$ ) in the Sallen-Key 2nd-order active low pass filter. As shown in Figure 14, resistors become capacitors, and capacitors become resistors. The resulted high pass filter has the same corner frequency and the same maximum gain as the previous $2 n d-o r d e r ~ l o w ~ p a s s ~ f i l t e r ~ i f ~ t h e ~ s a m e ~ c o m p o-~$ nents are chosen.


FIGURE 14. Sallen-Key 2nd-Order Active High-Pass Filter

### 4.4.4 State Variable Filter

A state variable filter requires three op amps. One convenient way to build state variable filters is with a quad op amp, such as the LMV324 (Figure 15).
This circuit can simultaneously represent a low-pass filter, high-pass filter, and bandpass filter at three different outputs. The equations for these functions are listed below. It is also called "Bi-Quad" active filter as it can produce a transfer function which is quadratic in both numerator and denominator.


FIGURE 15. State Variable Active Filter

## Application Notes (Continued)

$$
\begin{aligned}
& V_{L P}=\left(\frac{2 R_{3}}{R_{2}+R_{3}}\right) \frac{\frac{1}{R^{2} C^{2}}}{S^{2}+\frac{1}{\left(\frac{R_{2}+R_{3}}{2 R_{2}}\right) R C} S+\frac{1}{R^{2} C^{2}}} V_{I N} \\
& V_{H P}=\left(\frac{2 R_{3}}{R_{2}+R_{3}}\right) \frac{S^{2}}{S^{2}+\frac{1}{\left(\frac{R_{2}+R_{3}}{2 R_{2}}\right) R C} S+\frac{1}{R^{2} C^{2}}} V_{I N} \\
& V_{B P}=\left(\frac{2 R_{3}}{R_{2}+R_{3}}\right) \frac{\left(\frac{1}{R C}\right) S}{S^{2}+\frac{1}{\left(\frac{R_{2}+R_{3}}{2 R_{2}}\right) R C} S+\frac{1}{R^{2} C^{2}}} V_{I N}
\end{aligned}
$$

where for all three filters,

$$
\begin{gather*}
Q=\frac{R_{2}+R_{3}}{2 R_{2}}  \tag{11}\\
\omega_{0}=\frac{1}{R C} \quad \text { (resonant frequency) } \tag{12}
\end{gather*}
$$

A design example for a bandpass filter is shown below:
Assume the system design requires a bandpass filter with $f_{o}$ $=1 \mathrm{kHz}$ and $\mathrm{Q}=50$. What needs to be calculated are capacitor and resistor values.
First choose convenient values for $\mathrm{C}_{1}, \mathrm{R}_{1}$ and $\mathrm{R}_{2}$ :

$$
\begin{gathered}
\mathrm{C}_{1}=1200 \mathrm{pF} \\
2 \mathrm{R} 2=\mathrm{R}_{1}=30 \mathrm{k} \Omega
\end{gathered}
$$

Then from Equation (11),

$$
\begin{gathered}
R_{3}=R_{2}(2 Q-1) \\
R_{3}=15 \mathrm{k} \Omega \times(2 \times 50-1) \\
=1.5 \mathrm{M} \Omega
\end{gathered}
$$

From Equation (12),

$$
\begin{gathered}
R=\frac{1}{\omega_{0} C_{1}} \\
R=\frac{1}{\left(2 \pi \times 10^{3}\right)\left(1.2 \times 10^{-9}\right)} \\
=132.7 \mathrm{k} \Omega
\end{gathered}
$$

From the above calculated values, the midband gain is $\mathrm{H}_{0}=$ $R_{3} / R_{2}=100$ (40dB). The nearest 5\% standard values have been added to Figure 15.

### 4.5 Pulse Generators and Oscillators

A pulse generator is shown in Figure 16. Two diodes have been used to separate the charge and discharge paths to capacitor C .


DS 100060-81
FIGURE 16. Pulse Generator
When the output voltage $\mathrm{V}_{\mathrm{O}}$ is first at its high, $\mathrm{V}_{\mathrm{OH}}$, the capacitor C is charged toward $\mathrm{V}_{\mathrm{OH}}$ through $\mathrm{R}_{2}$. The voltage across $C$ rises exponentially with a time constant $\tau=\mathrm{R}_{2} \mathrm{C}$, and this voltage is applied to the inverting input of the op amp. Meanwhile, the voltage at the non-inverting input is set at the positive threshold voltage $\left(\mathrm{V}_{\mathrm{TH}_{+}}\right)$of the generator. The capacitor voltage continually increases until it reaches $\mathrm{V}_{\mathrm{TH}+}$, at which point the output of the generator will switch to its low, $\mathrm{V}_{\mathrm{OL}}$ ( $=0 \mathrm{~V}$ in this case). The voltage at the non-inverting input is switched to the negative threshold voltage ( $\mathrm{V}_{\text {TH }}$ ) of the generator. The capacitor then starts to discharge toward $\mathrm{V}_{\mathrm{OL}}$ exponentially through $\mathrm{R}_{1}$, with a time constant $\tau=\mathrm{R}_{1} \mathrm{C}$. When the capacitor voltage reaches $\mathrm{V}_{\text {TH. }}$, the output of the pulse generator switches to $\mathrm{V}_{\mathrm{OH}}$. The capacitor starts to charge, and the cycle repeats itself.

Application Notes


$$
\begin{aligned}
& T_{1}=R_{2} C \ln \frac{3 V_{O H}-V_{O L}-V^{+}}{2 V_{O H}-V^{+}} \text {and } T_{2}=R_{1} C \ln \frac{3 V_{\mathrm{OL}}-V_{\mathrm{OH}}-V^{+}}{2 V_{O L}-V^{+}} \\
& \text {When } V_{\mathrm{OL}}=0 \mathrm{~V} \\
& T_{1}=R_{2} C \ln \frac{3 \mathrm{~V}_{\mathrm{OH}}-\mathrm{V}^{+}}{2 \mathrm{~V}_{\mathrm{OH}}-\mathrm{V}^{+}} \quad \text { and } T_{2}=R_{1} C \ln \left(1+\frac{\mathrm{V}_{\mathrm{OH}}}{\mathrm{~V}^{+}}\right)
\end{aligned}
$$

## FIGURE 17. Waveforms of the Circuit in Figure 16

As shown in the waveforms in Figure 17, the pulse width $\left(\mathrm{T}_{1}\right)$ is set by $R_{2}, C$ and $V_{\mathrm{OH}}$, and the time between pulses $\left(T_{2}\right)$ is set by $R_{1}, C$ and $V_{\text {OL }}$. This pulse generator can be made to have different frequencies and pulse width by selecting different capacitor value and resistor values.
Figure 18 shows another pulse generator, with separate charge and discharge paths. The capacitor is charged through R1 and is discharged through $\mathrm{R}_{2}$.


FIGURE 18. Pulse Generator
Figure 19 is a squarewave generator with the same path for charging and discharging the capacitor.


FIGURE 19. Squarewave Generator

### 4.6 Current Source and Sink

The LMV321/358/324 can be used in feedback loops which regulate the current in external PNP transistors to provide current sources or in external NPN transistors to provide current sinks.

### 4.6.1 Fixed Current Source

A multiple fixed current source is show in Figure 20. A voltage $\left(V_{\text {REF }}=2 V\right)$ is established across resistor $R_{3}$ by the voltage divider ( $R_{3}$ and $R_{4}$ ). Negative feedback is used to cause the voltage drop across $R_{1}$ to be equal to $\mathrm{V}_{\text {REF }}$. This controls the emitter current of transistor $Q_{1}$ and if we neglect the base current of $Q_{1}$ and $Q_{2}$, essentially this same current is available out of the collector of $Q_{1}$.
Large input resistors can be used to reduce current loss and a Darlington connection can be used to reduce errors due to the $\beta$ of $Q_{1}$.
The resistor, $\mathrm{R}_{2}$, can be used to scale the collector current of $Q_{2}$ either above or below the 1 mA reference value.


FIGURE 20. Fixed Current Source

## Application Notes (Continued)

### 4.6.2 High Compliance Current Sink

A current sink circuit is shown in Figure 21. The circuit requires only one resistor $\left(R_{E}\right)$ and supplies an output current which is directly proportional to this resistor value.


FIGURE 21. High Compliance Current Sink

### 4.7 Power Amplifier

A power amplifier is illustrated in Figure 22. This circuit can provide a higher output current because a transistor follower is added to the output of the op amp.


FIGURE 22. Power Amplifier

### 4.8 LED Driver

The LMV321/358/324 can be used to drive an LED as shown in Figure 23.


FIGURE 23. LED Driver

### 4.9 Comparator with Hysteresis

The LMV321/358/324 can be used as a low power comparator. Figure 24 shows a comparator with hysteresis. The hysteresis is determined by the ratio of the two resistors.

$$
\begin{gathered}
\mathrm{V}_{\mathrm{TH}_{+}}=\mathrm{V}_{\mathrm{REF}} /\left(1+\mathrm{R}_{1} / \mathrm{R}_{2}\right)+\mathrm{V}_{\mathrm{OH}} /\left(1+\mathrm{R}_{2} / \mathrm{R}_{1}\right) \\
\mathrm{V}_{\mathrm{TH}-}=\mathrm{V}_{\mathrm{REF}} /\left(1+\mathrm{R}_{1} / \mathrm{R}_{2}\right)+\mathrm{V}_{\mathrm{OL}} /\left(1+\mathrm{R}_{2} / \mathrm{R}_{1}\right) \\
\mathrm{V}_{\mathrm{H}}=\left(\mathrm{V}_{\mathrm{OH}} \mathrm{~V}_{\mathrm{OL}}\right) /\left(1+\mathrm{R}_{2} / \mathrm{R}_{1}\right)
\end{gathered}
$$

where
$\mathrm{V}_{\mathrm{TH}+}$ : Positive Threshold Voltage
$\mathrm{V}_{\text {TH- }}$ : Negative Threshold Voltage
$\mathrm{V}_{\mathrm{OH}}$ : Output Voltage at High
$\mathrm{V}_{\mathrm{OL}}$ : Output Voltage at Low
$\mathrm{V}_{\mathrm{H}}$ : Hysteresis Voltage
Since LMV321/358/324 have rail-to-rail output, the ( $\mathrm{V}_{\mathrm{OH}} \mathrm{V}_{\mathrm{OL}}$ ) equals to $\mathrm{V}_{\mathrm{S}}$, which is the supply voltage.

$$
V_{H}=V_{S} /\left(1+R_{2} / R_{1}\right)
$$

The differential voltage at the input of the op amp should not exceed the specified absolute maximum ratings. For real comparators that are much faster, we recommend you to use National's LMV331/393/339, which are single, dual and quad general purpose comparators for low voltage operation.


FIGURE 24. Comparator with Hysteresis

## Connection Diagrams

5-Pin SC70-5/SOT23-5


Top View

8-Pin SO/MSOP


Top View

## Connection Diagrams (Continued)



## Ordering Information

| Package | Temperature Range | Packaging Marking | Transport Media | NSC Drawing |
| :---: | :---: | :---: | :---: | :---: |
|  | $\begin{gathered} \text { Industrial } \\ -40^{\circ} \mathrm{C} \text { to }+85^{\circ} \mathrm{C} \end{gathered}$ |  |  |  |
| 5-Pin SC70-5 | LMV321M7 | A12 | 1k Units Tape and Reel | MAA05 |
|  | LMV321M7X | A12 | 3k Units Tape and Reel |  |
| 5-Pin SOT23-5 | LMV321M5 | A13 | 1k Units Tape and Reel | MA05B |
|  | LMV321M5X | A13 | 3k Units Tape and Reel |  |
| 8-Pin Small Outline | LMV358M | LMV358M | Rails | M08A |
|  | LMV358MX | LMV358M | 2.5k Units Tape and Reel |  |
| 8-Pin MSOP | LMV358MM | LMV358 | 1k Units Tape and Reel | MUA08A |
|  | LMV358MMX | LMV358 | 3.5k Units Tape and Reel |  |
| 14-Pin Small Outline | LMV324M | LMV324M | Rails | M14A |
|  | LMV324MX | LMV324M | 2.5k Units Tape and Reel |  |
| 14-Pin TSSOP | LMV324MT | LMV324MT | Rails | MTC14 |
|  | LMV324MTX | LMV324MT | 2.5k Units Tape and Reel |  |

SC70-5 Tape and Reel Specification


## SOT-23-5 Tape and Reel Specification

TAPE FORMAT

| Tape Section | \# Cavities | Cavity Status | Cover Tape Status |
| :---: | :---: | :---: | :---: |
| Leader <br> Start End $)$ | $0(\mathrm{~min})$ | Empty | Sealed |
|  | $75(\mathrm{~min})$ | Empty | Sealed |
| Carrier | 3000 | Filled | Sealed |
|  | 250 | Filled | Sealed |
| Trailer | $125(\mathrm{~min})$ | Empty | Sealed |
| $($ Hub End $)$ | $0(\mathrm{~min})$ | Empty | Sealed |

TAPE DIMENSIONS


| 8 mm | 0.130 | 0.124 | 0.130 | 0.126 | $0.138 \pm 0.002$ | $0.055 \pm 0.004$ | 0.157 | $0.315 \pm 0.012$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $(3.3)$ | $(3.15)$ | $(3.3)$ | $(3.2)$ | $(3.5 \pm 0.05)$ | $(1.4 \pm 0.11)$ | $(4)$ | $(8 \pm 0.3)$ |
| Tape Size | DIM A | DIM Ao | DIM B | DIM Bo | DIM F | DIM Ko | DIM P1 | DIM W |

## SOT-23-5 Tape and Reel Specification <br> (Continued)

REEL DIMENSIONS


| 8 mm | 7.00 | 0.059 | 0.512 | 0.795 | 2.165 | $0.331+0.059 /-0.000$ | 0.567 | $\mathrm{~W} 1+0.078 /-0.039$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 330.00 | 1.50 | 13.00 | 20.20 | 55.00 | $8.40+1.50 /-0.00$ | 14.40 | $\mathrm{~W} 1+2.00 /-1.00$ |
| Tape Size | A | B | C | D | N | W 1 | W 2 | W 3 |

Physical Dimensions inches (millimeters) unless otherwise noted


LAND PATTERN RECOMMENDATION


Physical Dimensions inches (millimeters) unless otherwise noted (Continued)


Physical Dimensions inches (millimeters) unless otherwise noted (Continued)


8-Pin MSOP
Order Number LMV358MM and LMV358MMX
NS Package Number MUA08A

Physical Dimensions inches (millimeters) unless otherwise noted (Continued)


Physical Dimensions inches (millimeters) unless otherwise noted (Continued)


## 14-Pin TSSOP Order Number LMV324MT and LMV324MTX NS Package Number MTC14

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